

Some analytical methods and applications in electrical engineering

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Introduction



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Maxwell's equations



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Some analytical applications (linear case)

Electromagnetic Field and Eddy Current Losses in Bushing
Regions of Transformers

Temperature distribution in the bushing region of tank wall



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Nonlinear problems

- Analytical model for nonlinear permeability. Effective nonlinear permeability
- Nonlinear permeability and nonlinear oscillations of the magnetic field.
- Electromagnetic Field and Eddy Current Losses in Bushing Regions of Transformers. Nonlinear problem.



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Electromagnetic devices

► Transformers



Electromagnetic devices

- ▶ Transformers



- ▶ Electric motors and generators



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- ▶ Transformers



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- ▶ Magnetic levitation systems



Electromagnetic devices

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- ▶ Magnetic levitation systems



- ▶ Household appliances



Electromagnetic field distribution in transformers

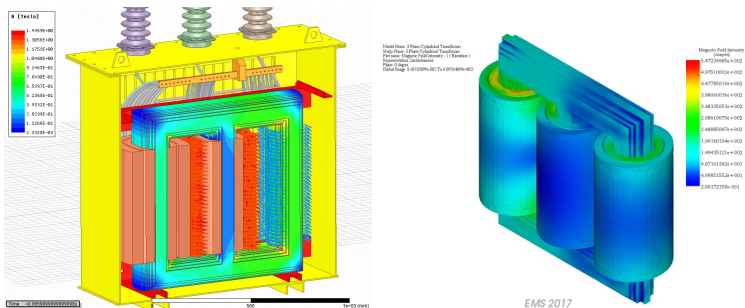


Figure 1: Magnetic field distribution in a transformer



Temperature distribution in transformers

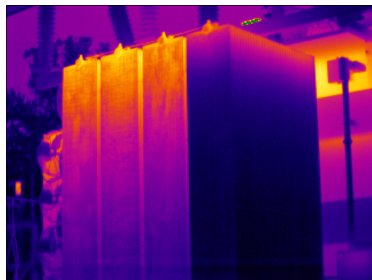
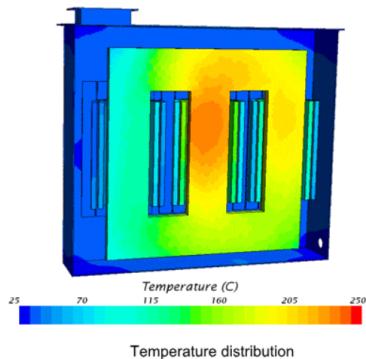


Figure 2: Calculated and measured temperature distribution in a transformer



Magnetic field distribution in electric motors

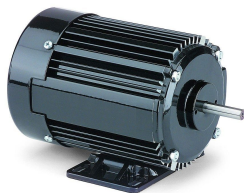


Figure 3: Electric motor

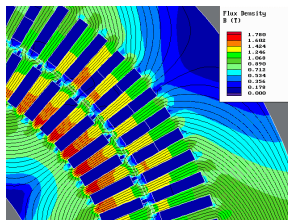


Figure 4: Magnetic field distribution in a motor core



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James Clerk Maxwell

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Modern form of Maxwell’s equations (Heaviside, Hertz and Gibbs, 1884):

$$\begin{aligned}\nabla \cdot \mathbf{D} &= \rho, & \nabla \times \mathbf{E} &= -\frac{\partial \mathbf{B}}{\partial t}, \\ \nabla \cdot \mathbf{B} &= 0, & \nabla \times \mathbf{H} &= \mathbf{j} + \frac{\partial \mathbf{D}}{\partial t}.\end{aligned}$$

Constitutive equations:

$$\mathbf{D} = \varepsilon_0 \varepsilon_r \mathbf{E}, \quad \mathbf{B} = \mu_0 \mu_r \mathbf{H}.$$



Maxwell's equations. Low frequency approximation

Mainly, in the problems of electric engineering:

$$L \ll \lambda = \frac{c}{f}, \quad \implies \quad f \ll \frac{c}{L}.$$

$$\rho = 0, \quad \mathbf{j} = \sigma \mathbf{E} + \mathbf{J}.$$

In the low frequency limit:

$$\nabla \cdot \mathbf{D} = 0, \quad \nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t},$$

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Vector and scalar potentials:

$$\nabla \cdot \mathbf{B} = 0 \quad \Rightarrow \quad \mathbf{B} = \nabla \times \mathbf{A} \quad \Rightarrow \quad \nabla \times \left(\mathbf{E} + \frac{\partial \mathbf{A}}{\partial t} \right) = 0$$



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$$\Rightarrow \quad \mathbf{E} + \frac{\partial \mathbf{A}}{\partial t} = -\nabla \varphi.$$

Thus,

$$\mathbf{E} = -\nabla \varphi - \frac{\partial \mathbf{A}}{\partial t}, \quad \mathbf{B} = \nabla \times \mathbf{A}.$$



Maxwell's equations

In terms of magnetic field \mathbf{H} :

$$\nabla \times \mathbf{H} = \sigma \mathbf{E} + \mathbf{J}$$

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$$\left. \begin{aligned} \nabla \times \nabla \times \mathbf{H} &= \nabla (\nabla \cdot \mathbf{H}) - \nabla^2 \mathbf{H}, \\ \nabla \times \mathbf{E} &= -\frac{\partial(\mu_0 \mu_r \mathbf{H})}{\partial t}, \end{aligned} \right\} \Rightarrow$$



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Bushing region of transformer

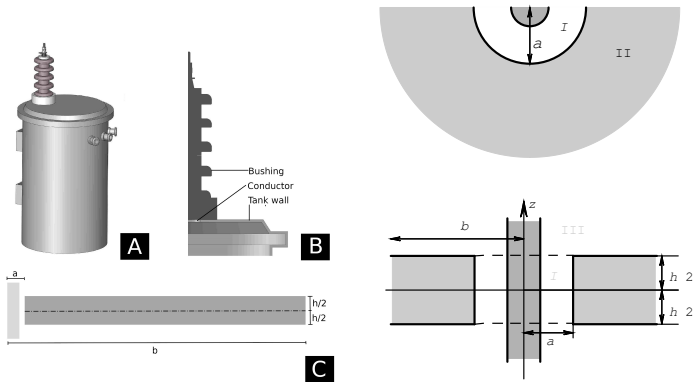


Figure 5: Bushing region of a transformer



Bushing region of transformer

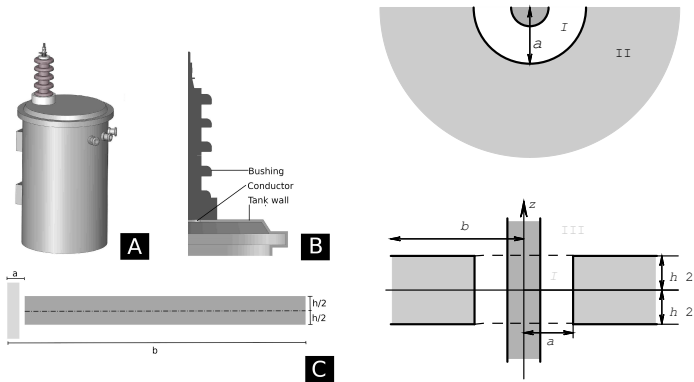


Figure 5: Bushing region of a transformer

AC in the conductor: $I(t) = \text{Re}\{Ie^{j\omega t}\}$,



Bushing region of transformer

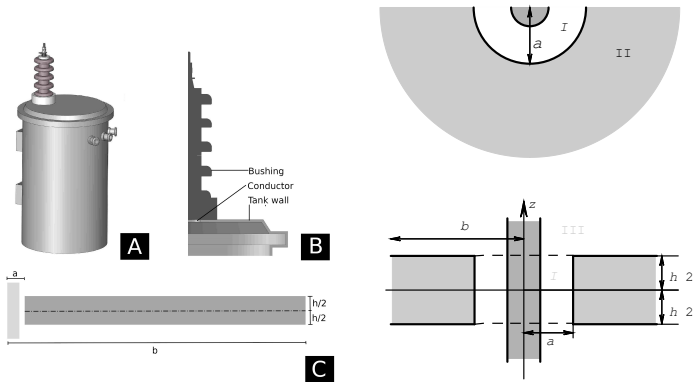


Figure 5: Bushing region of a transformer

AC in the conductor: $I(t) = \text{Re}\{Ie^{j\omega t}\}$,
where I is the amplitude.



Magnetic field inside the tank wall

Axial symmetry \implies Cylindrical coordinates



Magnetic field inside the tank wall

Axial symmetry \implies Cylindrical coordinates

In the frequency domain:

$$\left\{ \begin{array}{l} \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial H}{\partial r} \right) + \frac{\partial^2 H}{\partial z^2} - \frac{H}{r^2} - \beta^2 H = 0, \\ H(r, \pm h/2) = \frac{I}{2\pi r}, \\ H(a, z) = \frac{I}{2\pi a}, \end{array} \right.$$

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Analytical solution:

$$H(r, z) = \frac{I}{2\pi a} \left\{ \frac{a}{r} \frac{\cosh(\beta z)}{\cosh(\beta h/2)} + \frac{4\beta^2}{\pi} \sum_{n=0}^{\infty} \frac{(-1)^n}{\lambda_n^2 (2n+1)} \frac{K_1(\lambda_n r)}{K_1(\lambda_n a)} \cos\left(\frac{\pi(2n+1)}{h} z\right) \right\},$$



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where $\lambda^2 = \beta^2 + \left(\frac{\pi(2n+1)}{h} z\right)^2$, $n = 0, 1, 2, \dots$



Electric field inside the tank wall

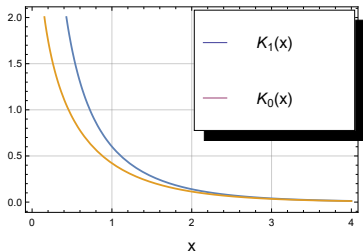


Figure 6: Modified Bessel functions $K_1(x)$ and $K_0(x)$.

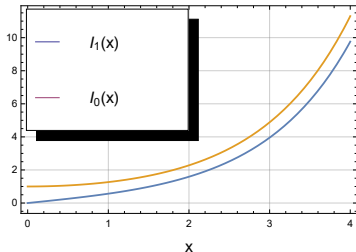


Figure 7: Modified Bessel functions $I_1(x)$ and $I_0(x)$.



Electric field inside the tank wall

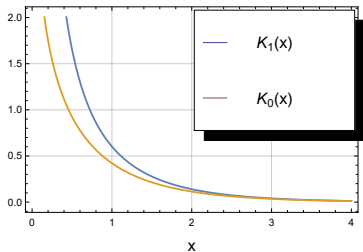
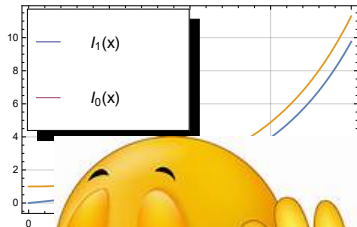


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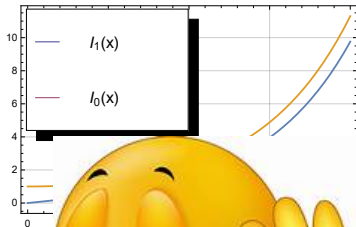
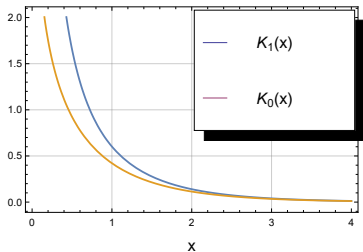


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$$E_r(r, z) = -\frac{\beta I}{\sigma 2\pi a} \left\{ \frac{a \sinh(\beta z)}{r \cosh(\beta h/2)} - \frac{4\beta}{h} \sum_{n=0}^{\infty} \frac{(-1)^n K_1(\lambda_n r)}{\lambda_n^2 K_1(\lambda_n a)} \sin\left(\frac{\pi(2n+1)}{h} z\right) \right\}.$$



Electric field inside the tank wall

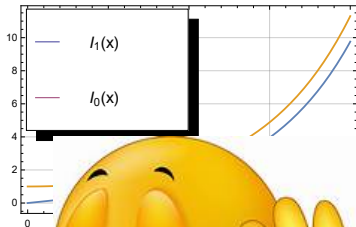
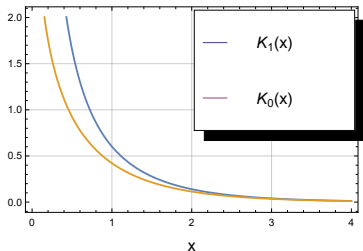


Figure 6: Modified Bessel functions $K_1(x)$ and $K_0(x)$.



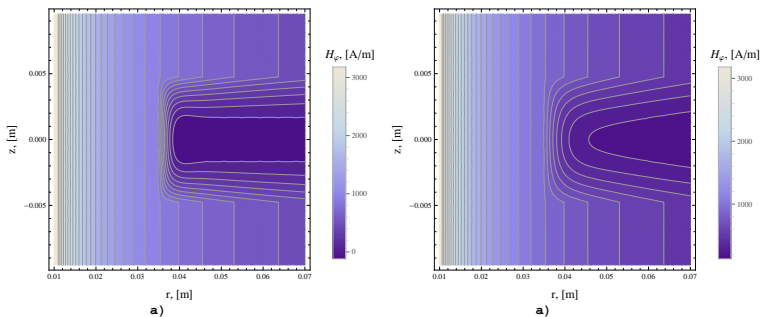
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$$E_z(r, z) = -\frac{4\beta^2 I}{\pi\sigma 2\pi a} \sum_{n=0}^{\infty} \frac{(-1)^n K_0(\lambda_n r)}{\lambda_n(2n+1) K_1(\lambda_n a)} \cos\left(\frac{\pi(2n+1)z}{h}\right)$$



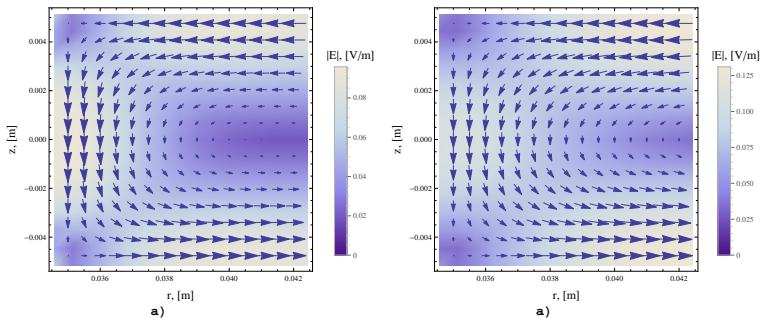
Magnetic field penetration into the tank wall

Figure 8: Magnetic field penetration in the tank wall for $\mu_r = 200$. Case 1. $\sigma = 4 \times 10^6 (\Omega m)^{-1}$. Case 2. $\sigma = 1.33 \times 10^6 (\Omega m)^{-1}$.



Electric field distribution in the tank wall

Figure 9: Electric field distribution in the tank wall for $\mu_r = 200$. Case 1. $\sigma = 4 \times 10^6 (\Omega m)^{-1}$. Case 2. $\sigma = 1.33 \times 10^6 (\Omega m)^{-1}$.

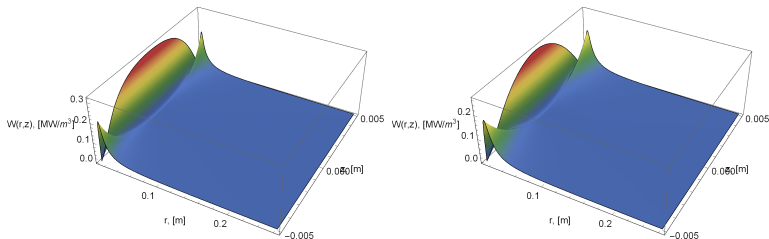


Power losses density in the tank wall

Eddy current losses in the tank wall (average per period of oscillations T):

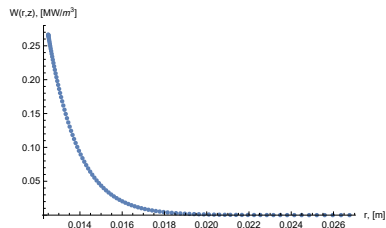
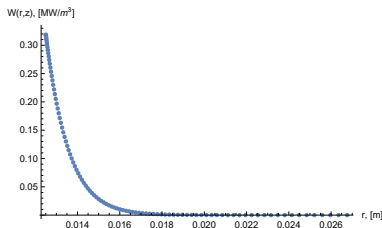
$$W(r, z) = \frac{1}{T} \int_0^T \sigma \mathbf{E}^2(r, z, t) dt = \frac{1}{2} \sigma (|E_r(r, z)|^2 + |E_z(r, z)|^2).$$

Figure 10: Power losses distribution in the tank wall for $\mu_r = 200$. Case 1. $\sigma = 4 \times 10^6 (\Omega m)^{-1}$. Case 2. $\sigma = 1.33 \times 10^6 (\Omega m)^{-1}$.



Power losses density in the center of the tank wall

Figure 11: Power losses density in the center of the tank wall for $\mu_r = 200$.
Case 1. $\sigma = 4 \times 10^6 (\Omega m)^{-1}$. Case 2. $\sigma = 1.33 \times 10^6 (\Omega m)^{-1}$.



Temperature distribution in the tank wall

Heat equation: $\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial T}{\partial r} \right) + \frac{\partial^2 T}{\partial z^2} = -\frac{1}{k_t} W(r, z).$

Boundary conditions:

$$\begin{aligned} \left(k_t \frac{\partial T}{\partial r} - h_{c1} (T - T_{a1}) \right) \Big|_{r=a} &= 0, & \left(k_t \frac{\partial T}{\partial r} + h_{c2} (T - T_{a2}) \right) \Big|_{r=b} &= 0, \\ \left(k_t \frac{\partial T}{\partial z} + h_{c3} (T - T_{a3}) \right) \Big|_{z=\frac{h}{2}} &= 0, & \left(k_t \frac{\partial T}{\partial z} - h_{c4} (T - T_{a4}) \right) \Big|_{z=-\frac{h}{2}} &= 0. \end{aligned}$$



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Parameters	Values	Parameters	Values
μ_T	500	h_{c4}	35 W/m ² K
k_t	16 W/mK	T_{a1}	80 °C
f	50 s ⁻¹	T_{a2}	18 °C
h_{c1}	25 W/m ² K	T_{a3}	18 °C
h_{c2}	10 W/m ² K	T_{a4}	80 °C
h_{c3}	10 W/m ² K		



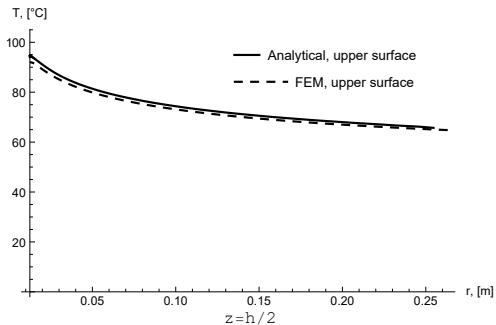


Figure 12: Temperature profiles on the upper surface.

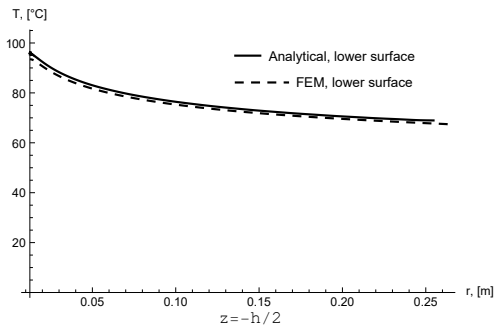


Figure 13: Temperature profiles on the lower surface.



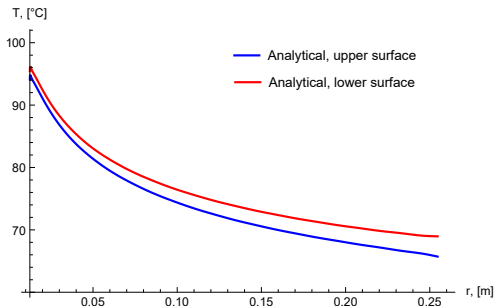


Figure 14: Temperature profiles on the upper and lower surfaces. Vertical temperature gradient.

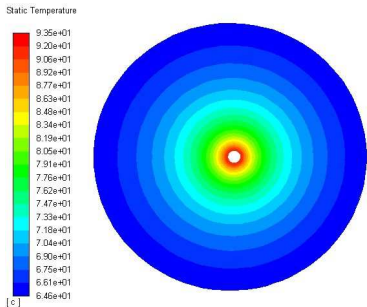


Figure 15: 2D temperature distribution. FEM-simulations.



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 - ▶ prediction and estimation of hot spots and other hazards



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- ▶ Analytical formulae provide high precision results such as:
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 - ▶ estimation of temperature distributions in the vital parts of transformers
 - ▶ prediction and estimation of hot spots and other hazards
- ▶ Analytical method do not need of expensive computational resources.



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Maxwell's equations in media with nonlinear permeability

$$\left\{ \begin{array}{l} \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial H}{\partial r} \right) + \frac{\partial^2 H}{\partial z^2} - \frac{H}{r^2} - \sigma \frac{\partial(\mu H)}{\partial t} = 0, \\ H(r, \pm h/2) = \frac{I}{2\pi r}, \\ H(a, z) = \frac{I}{2\pi a}, \end{array} \right.$$

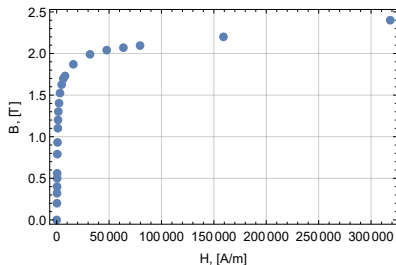
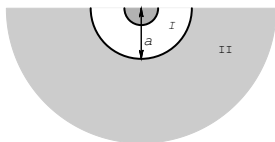


Figure 16: Magnetization points for 1010 low carbon steel.

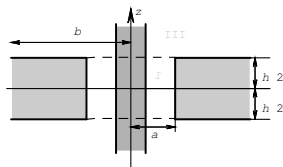


Figure 17: Bushing region of a transformer



Analytical approximation for nonlinear permeability.



Analytical approximation for nonlinear permeability.

Analytical calculations need of an analytical form of the magnetization curve.

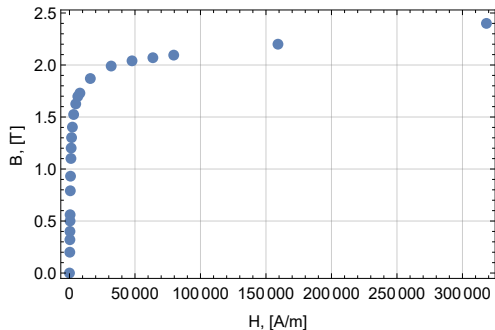
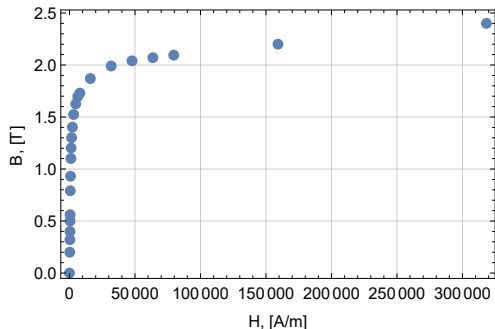


Figure 18: Magnetization points for 1010 low carbon steel.



Analytical approximation for nonlinear permeability.

Analytical calculations need of an analytical form of the magnetization curve.



Analytical approximation for nonlinear permeability.

Least squares method minimizes the sum of the squared errors:



Analytical approximation for nonlinear permeability.

Least squares method minimizes the sum of the squared errors:

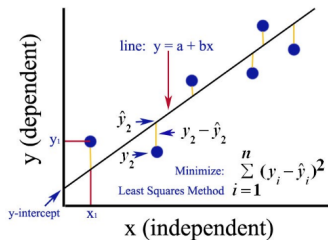


Figure 19: Least squares method minimizes the sum of the squared errors.



Analytical approximation for nonlinear permeability.

Least squares method minimizes the sum of the squared errors:

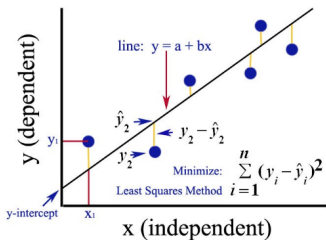


Figure 19: Least squares method minimizes the sum of the squared errors.

To be minimized:

$$L[\gamma_1, \gamma_2, \gamma_3] = \sum_{k=1}^N \left\{ B_k - \mu_0 (\gamma_1 \arctan(\gamma_2 H_k) + \gamma_3 H_k) \right\}^2.$$



Analytical approximation for nonlinear permeability.

Least squares method minimizes the sum of the squared errors:

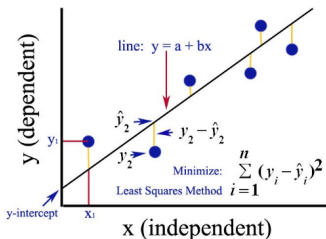


Figure 19: Least squares method minimizes the sum of the squared errors.

To be minimized:

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The result of minimization:

$$\gamma_1 = 999637.86 \text{ A/m}$$

$$\gamma_2 = 0.001002 \text{ (A/m)}^{-1}$$

$$\gamma_3 = 1.0861$$



Analytical approximation for nonlinear permeability.

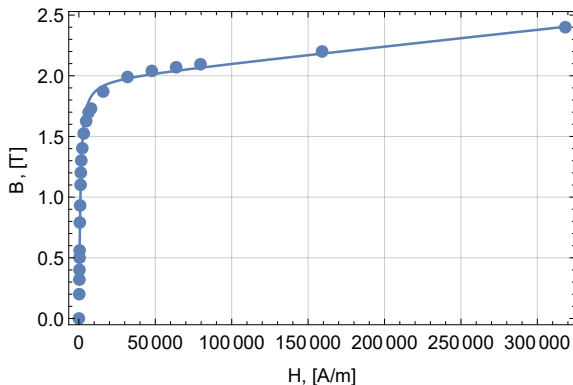


Figure 20: Magnetization curve: analytical result vs. experimental points.

Relative error $< 1\%$.



Nonlinear oscillations.

Consider the magnetic field of harmonic form:

$$H = H_1 e^{j\omega t} + H_{-1} e^{-j\omega t}, \quad \text{where } H_1 \in \mathbb{C}.$$



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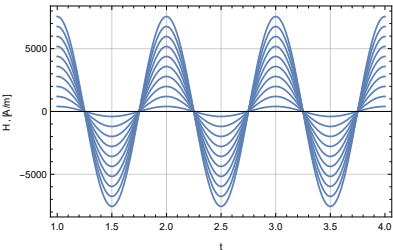


Figure 21: Harmonic oscillations of H

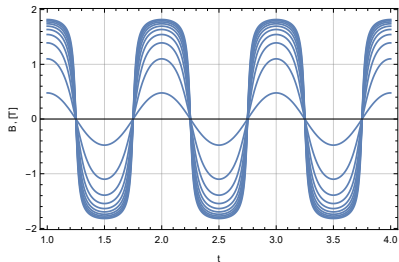


Figure 22: Nonlinear oscillations of B



Nonlinear oscillations.

Consider the magnetic field of harmonic form:
 $H = H_1 e^{j\omega t} + H_{-1} e^{-j\omega t}$, where $H_1 \in \mathbb{C}$.

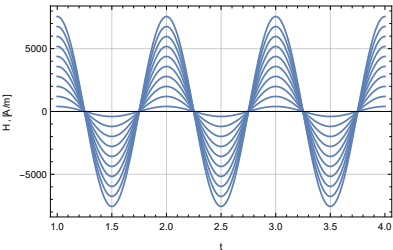


Figure 21: Harmonic oscillations of H

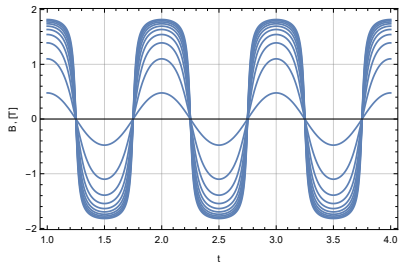


Figure 22: Nonlinear oscillations of B

**Oscillations in a nonlinear system
lead to appearance of higher harmonics**



Nonlinear permeability: Fourier expansion

$$H(t) = H_1 e^{j\omega t} + H_{-1} e^{-j\omega t}$$

→

$$B(t) = \mu_0 (\gamma_1 \arctan(\gamma_2 H(t)) + \gamma_3 H(t))$$



Expansion in a Fourier series



Nonlinear permeability: Fourier expansion

$$H(t) = H_1 e^{j\omega t} + H_{-1} e^{-j\omega t}$$

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$$B(t) = \mu_0 (\gamma_1 \arctan(\gamma_2 H(t)) + \gamma_3 H(t))$$



Expansion in a Fourier series

Complex Fourier series:

$$B(t) = \sum_{n=-\infty}^{+\infty} B_n e^{jn\omega t},$$



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where

$$B_n = \frac{\omega}{2\pi} \int_0^{2\pi/\omega} \mu_0 (\gamma_1 \arctan(\gamma_2 H(t)) + \gamma_3 H(t)) dt.$$



Nonlinear permeability: Fourier expansion

$$H(t) = H_1 e^{j\omega t} + H_{-1} e^{-j\omega t}$$

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Expansion in a Fourier series

Complex Fourier series:

where

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Nonlinear permeability: Fourier expansion



Nonlinear permeability: Fourier expansion

$$H = H_1 e^{j\omega t} + H_{-1} e^{-j\omega t}$$

→

$$\frac{\partial B}{\partial t} = \mu_0 \left(\frac{\gamma_1 \gamma_2}{1 + (\gamma_2 H)^2} + \gamma_3 \right) \frac{\partial H}{\partial t}$$

Expansion in a power series
with respect to $e^{j\omega t}$

Reconstruction of $B(t)$:

$$B(t) = \int \frac{\partial B}{\partial t} dt + C$$



Nonlinear permeability: Fourier expansion

$$H = H_1 e^{j\omega t} + H_{-1} e^{-j\omega t}$$

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Expansion in a power series
with respect to $e^{j\omega t}$

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$$B(t) = \int \frac{\partial B}{\partial t} dt + C$$



$$\frac{1}{1 + (\gamma_2 H)^2} = \frac{1}{1 + (\gamma_2 H_1 e^{j\omega t} + \gamma_2 H_{-1} e^{-j\omega t})^2}$$
$$= \frac{1}{1 + 2|\gamma_2 H_1|^2 + (\gamma_2 H_1)^2 e^{2j\omega t} + (\gamma_2 H_{-1})^2 e^{-2j\omega t}},$$



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where

$$1 + 2|\gamma_2 H_1|^2 > |(\gamma_2 H_1)^2 e^{2j\omega t} + (\gamma_2 H_{-1})^2 e^{-2j\omega t}|$$



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This allows expansion in a geometric progression:

$$\frac{1}{a + z} = \sum_{n=0}^{\infty} \frac{(-1)^n}{a^{n+1}} z^n \quad \text{if } |a| > |z|.$$



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$$\frac{1}{1 + (\gamma_2 H)^2} \frac{\partial H}{\partial t} = j\omega (H_1 e^{j\omega t} - H_{-1} e^{-j\omega t})$$

$$\times \sum_{n=0}^{\infty} \frac{(-1)^n [(\gamma_2 H_1)^2 e^{2j\omega t} + (\gamma_2 H_{-1})^2 e^{-2j\omega t}]^n}{(1 + 2|\gamma_2 H_1|^2)^{n+1}}$$



$$\frac{1}{1 + (\gamma_2 H)^2} = \frac{1}{1 + (\gamma_2 H_1 e^{j\omega t} + \gamma_2 H_{-1} e^{-j\omega t})^2}$$

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$$(x + y)^n = \sum_{m=0}^n C_n^m x^m y^{n-m}, \quad \text{where } C_n^m = \frac{n!}{m!(n-m)!}.$$



$$\begin{aligned}
& \frac{1}{1 + (\gamma_2 H)^2} \frac{\partial H}{\partial t} \\
&= \sum_{k=0}^{\infty} (-1)^k j\omega \left[H_1 (\gamma_2 H_1)^{2k} e^{(2k+1)j\omega t} - H_{-1} (\gamma_2 H_{-1})^{2k} e^{-(2k+1)j\omega t} \right] \\
&\times \sum_{m=0}^{\infty} \left[\frac{C_{2m+k}^m |\gamma_2 H_1|^{4m}}{(1 + 2|\gamma_2 H_1|^2)^{2m+k+1}} + \frac{C_{2m+k+1}^m |\gamma_2 H_1|^{2(2m+1)}}{(1 + 2|\gamma_2 H_1|^2)^{2m+k+2}} \right],
\end{aligned}$$



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\end{aligned}$$

where

$$\begin{aligned}
& \sum_{m=0}^{\infty} \left[\frac{C_{2m+k}^m z^{4m}}{(1 + 2z^2)^{2m+k+1}} + \frac{C_{2m+k+1}^m z^{2(2m+1)}}{(1 + 2z^2)^{2m+k+2}} \right] \\
&= \frac{\sqrt{1 + 4z^2} - 1}{2z^2} \frac{2^k}{\left[1 + 2z^2 + \sqrt{1 + 4z^2} \right]^k}.
\end{aligned}$$



Finally,

$$\begin{aligned}\frac{\partial B}{\partial t} &= \mu_0 \left(\frac{\gamma_1 \gamma_2}{1 + (\gamma_2 H)^2} + \gamma_3 \right) \frac{\partial H}{\partial t} \\ &= \mu_0 \gamma_1 \gamma_2 \frac{\sqrt{1 + 4|\gamma_2 H_1|^2} - 1}{2|\gamma_2 H_1|^2} \\ &\times \sum_{k=0}^{\infty} j\omega \left[H_1 (\gamma_2 H_1)^{2k} e^{(2k+1)j\omega t} - H_{-1} (\gamma_2 H_{-1})^{2k} e^{-(2k+1)j\omega t} \right] \\ &\times (-2)^k \left[1 + 2|\gamma_2 H_1|^2 + \sqrt{1 + 4|\gamma_2 H_1|^2} \right]^{-k}, \\ &+ \mu_0 \gamma_3 j\omega (H_1 e^{j\omega t} - H_{-1} e^{-j\omega t})\end{aligned}$$



Finally,

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Thus, the magnetic field B can be reconstructed as follows:

$$B = \int \frac{\partial B}{\partial t} dt + C,$$



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Thus, the magnetic field B can be reconstructed as follows:

$$B = \int \frac{\partial B}{\partial t} dt + C,$$

where

$$C : \lim_{H \rightarrow 0} B = 0 \implies C = 0.$$



Effective permeability.

As a result,

$$B(t) = \sum_{k=0}^{\infty} \left\{ \mu_{2k+1}^{\text{eff}} H_1 e^{j(2k+1)\omega t} + \bar{\mu}_{2k+1}^{\text{eff}} H_{-1} e^{-j(2k+1)\omega t} \right\}.$$



Effective permeability.

As a result,

$$B(t) = \sum_{k=0}^{\infty} \left\{ \mu_{2k+1}^{\text{eff}} H_1 e^{j(2k+1)\omega t} + \bar{\mu}_{2k+1}^{\text{eff}} H_{-1} e^{-j(2k+1)\omega t} \right\}.$$

For the basic harmonic:

$$\mu_1^{\text{eff}} = \mu_0 \left[\gamma_1 \gamma_2 \frac{\sqrt{1 + 4|\gamma_2 H_1|^2} - 1}{2|\gamma_2 H_1|^2} + \gamma_3 \right].$$

And for the rest of harmonics:

$$\begin{aligned} \mu_{2k+1}^{\text{eff}} &= \mu_0 \gamma_1 \gamma_2 \frac{\sqrt{1 + 4|\gamma_2 H_1|^2} - 1}{2|\gamma_2 H_1|^2} \\ &\times \frac{(-2)^k (\gamma_2 H_1)^{2k}}{(2k + 1) \left[1 + 2|\gamma_2 H_1|^2 + \sqrt{1 + 4|\gamma_2 H_1|^2} \right]^k} \end{aligned}$$



Magnetization curves for different harmonics.

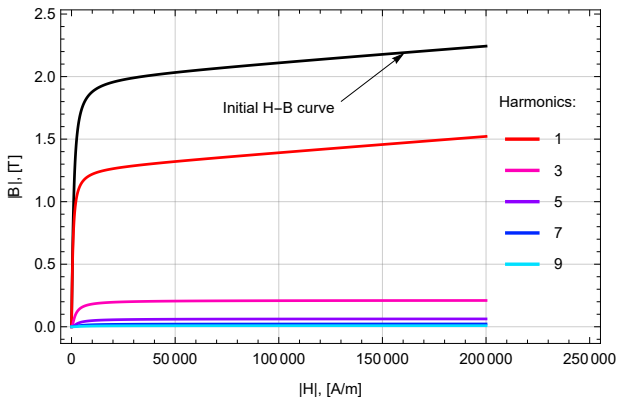


Figure 23: Magnetization curves for different harmonics



Magnetic field inside the tank wall

$$\left\{ \begin{array}{l} \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial H}{\partial r} \right) + \frac{\partial^2 H}{\partial z^2} - \frac{H}{r^2} - \beta^2 H = f(H), \\ H(r, \pm h/2) = \frac{I}{2\pi r}, \\ H(a, z) = \frac{I}{2\pi a}, \end{array} \right.$$

where $\beta^2 = j\omega\sigma\mu_0(\gamma_1\gamma_2 + \gamma_3) = j\omega\sigma\mu_0 \times 1001.64$,

$$f(z) = -j\omega\sigma\mu_0\gamma_1\gamma_2 \frac{1 + 2(\gamma_2|H|)^2 - \sqrt{1 + 4(\gamma_2|H|)^2}}{2(\gamma_2|H|)^2} H \\ \sim -j\omega\sigma\mu_0\gamma_1\gamma_2^3|H|^2 H$$

$$\gamma_1 = 999637.86 \text{ A/m}$$

$$\gamma_2 = 0.001002 \text{ (A/m)}^{-1}$$

$$\gamma_3 = 1.0861$$



Solution to the nonlinear problem

$$H(r, z) = H_{\text{lin}}(r, z) + \int_{-h/2}^{h/2} \int_a^b G(r, \rho; z - \zeta) f(H(\rho, \zeta)) \rho d\rho d\zeta,$$



Solution to the nonlinear problem

$$H(r, z) = H_{\text{lin}}(r, z) + \int_{-h/2}^{h/2} \int_a^b G(r, \rho; z - \zeta) f(H(\rho, \zeta)) \rho d\rho d\zeta,$$

where the solution to the linear problem:

$$H_{\text{lin}}(r, z) = \frac{l}{2\pi a} \left\{ \frac{a \cosh(\beta z)}{r \cosh(\beta h/2)} + \frac{4\beta^2}{\pi} \sum_{n=0}^{\infty} \frac{(-1)^n}{\lambda_n^2 (2n+1)} \frac{K_1(\lambda_n r)}{K_1(\lambda_n a)} \cos\left(\frac{\pi(2n+1)}{h} z\right) \right\},$$



Solution to the nonlinear problem

$$H(r, z) = H_{\text{lin}}(r, z) + \int_{-h/2}^{h/2} \int_a^b G(r, \rho; z - \zeta) f(H(\rho, \zeta)) \rho d\rho d\zeta,$$

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Green's function:

$$G(r, \rho; z) = \frac{2}{h} \sum_{n=0}^{\infty} \left\{ \frac{I_1(\lambda_n a)}{K_1(\lambda_n a)} K_1(\lambda_n r) K_1(\lambda_n \rho) - K_1(\lambda_n r) I_1(\lambda_n \rho) \theta(r - \rho) - K_1(\lambda_n \rho) I_1(\lambda_n r) \theta(\rho - r) \right\} \cos\left(\frac{\pi(2n+1)}{h} z\right)$$



Solution to the nonlinear problem

In a symbolic form:

$$\mathbf{H} = \mathbf{H}_{\text{lin}} + \mathbf{G} \cdot f(\mathbf{H}).$$

Iterations:

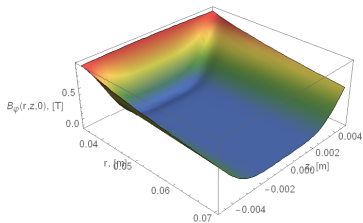
$$\begin{aligned} \mathbf{H}_{n+1} &= \mathbf{H}_{\text{lin}} + \mathbf{G} \cdot f(\mathbf{H}_n), & \mathbf{H}_0 &= \mathbf{H}_{\text{lin}}. \\ \text{If } \exists \lim_{n \rightarrow \infty} \mathbf{H}_n, & \lim_{n \rightarrow \infty} \mathbf{H}_{n+1} &= \mathbf{H}_{\text{lin}} + \mathbf{G} \cdot f\left(\lim_{n \rightarrow \infty} \mathbf{H}_n\right). \end{aligned}$$

Convergence. Contraction mapping theorem:

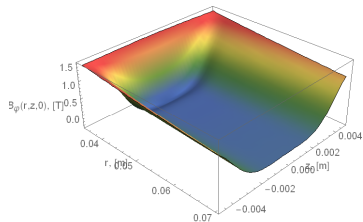
$$\begin{aligned} \exists q < 1 : \quad & \|\mathbf{H}_{n+1} - \mathbf{H}_n\| \leq \|\mathbf{G}\| \cdot \|f(\mathbf{H}_n) - f(\mathbf{H}_{n-1})\| \\ & < q \|\mathbf{H}_n - \mathbf{H}_{n-1}\|, \text{ where } \|\mathbf{H}_n\| = \sup_{\substack{r \in [a, b] \\ z \in [-h/2, h/2]}} |H(r, z)|. \end{aligned}$$



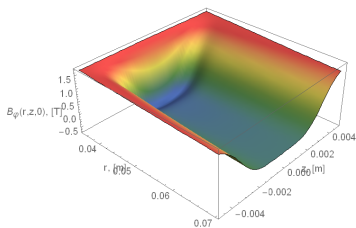
Magnetic field penetration into the tank wall. Nonlinear problem



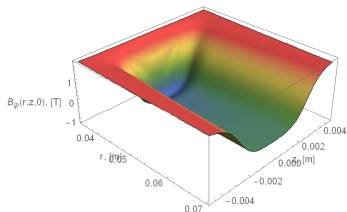
a)



b)



c)

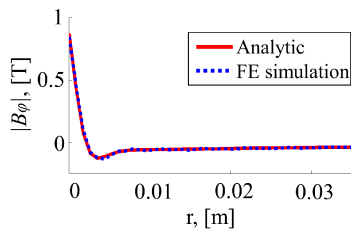


d)

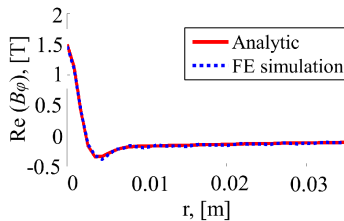
Figure 24: Wave forms of magnetic flux density: a) 176.77 A, b) 500 A, c) 1000 A, d) 1500 A.



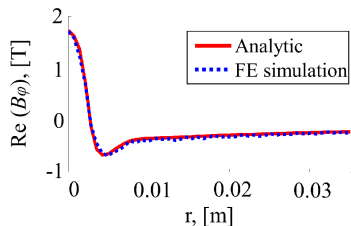
Magnetic field penetration into the tank wall. Analytical solution vs. FEM



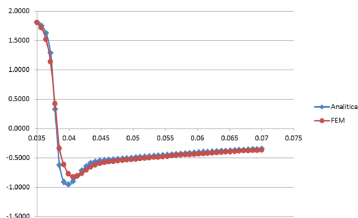
a)



b)



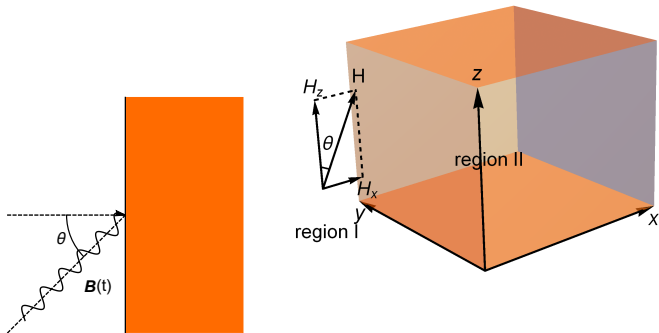
c)



d)

Figure 25: Analytical solution vs. FEM: a) 176.77 A, b) 500 A, c) 1000 A, d) 1500 A.





$$\mathbf{H} = H_x(x)\mathbf{e}_x + H_z(x)\mathbf{e}_z.$$

$$\gamma_2 \mathbf{H} = \mathbf{h} = h_x \mathbf{e}_x + h_z \mathbf{e}_z.$$

$$\mu_r(|\mathbf{h}|) = \gamma_1 \gamma_2 \frac{\sqrt{1 + 4|\mathbf{h}|^2} - 1}{2|\mathbf{h}|^2} + \gamma_3,$$

where

$$|\mathbf{h}| = \sqrt{h_x^2 + h_z^2}.$$



Maxwell's equations yield:

$$\frac{d^2 h_z}{dx^2} = j\omega\sigma\mu_0\mu_r(|\mathbf{h}|)h_z, \quad (1)$$

$$\frac{d}{dx} \left\{ \mu_r(|\mathbf{h}|)h_x \right\} = 0. \quad (2)$$

Eqs. (1) and (2) are coupled through $\mu_r(|\mathbf{h}|)$.

Boundary conditions are:

$$h_z|_{\text{II}} = h_z|_{\text{I}} \equiv \mathbf{a}_z,$$
$$\mu_r(|\mathbf{h}|)h_x|_{\text{II}} = h_x|_{\text{I}} \equiv \mathbf{a}_x.$$

Integral of Eq. (2):

$$\mu_r(|\mathbf{h}|)h_x = \text{const} = \mathbf{a}_x,$$

wherefrom

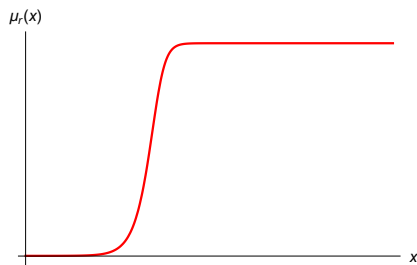
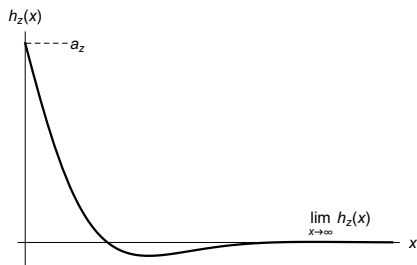
$$h_x(x) = \frac{\mathbf{a}_x}{\frac{2\gamma_1\gamma_2 \left(1 - (|\mathbf{a}_x|/\gamma_1\gamma_2)^2\right)}{1 + \sqrt{1 + 4|h_z(x)|^2 \left(1 - (|\mathbf{a}_x|/\gamma_1\gamma_2)^2\right)}} + \gamma_3}.$$



Analysis of asymptotic behavior

$$\frac{d^2 h_z}{dx^2} = j\omega\sigma\mu_0\mu_r(h_z)h_z,$$

$$\mu_r(h_z) = \frac{2\gamma_1\gamma_2 \left(1 - (|a_x|/\gamma_1\gamma_2)^2\right)}{1 + \sqrt{1 + 4|h_z|^2 \left(1 - (|a_x|/\gamma_1\gamma_2)^2\right)}} + \gamma_3.$$



Analysis of asymptotic behavior

In the limit $x \rightarrow \infty$:

$$\frac{d^2 h_z}{dx^2} = 2j\alpha_\infty^2 h_z,$$

Near the surface ($x \rightarrow 0$)

$$\frac{d^2 h_z}{dx^2} = 2j\alpha_s^2 h_z,$$

$$\alpha_s = \sqrt{\frac{\omega\sigma\mu_0\mu_s}{2}}.$$

Asymptotic solution:

$$h_z(x) \sim e^{-(1+j)\alpha_s x}.$$

$$\alpha_\infty = \lim_{x \rightarrow \infty} \sqrt{\frac{\omega\sigma\mu_0\mu_{\text{eff}}(|h_z(x)|)}{2}} \\ = \sqrt{\alpha_0^2 + \alpha_1^2},$$

$$\alpha_0 = \sqrt{\frac{\omega\sigma\mu_0\gamma_1\gamma_2}{2} \left(1 - (|a_x|/\gamma_1\gamma_2)^2\right)},$$

$$\alpha_1 = \sqrt{\frac{\omega\sigma\mu_0\gamma_3}{2}}.$$

Asymptotic solution:

$$h_z(x) \sim e^{-(1+j)\alpha_\infty x}.$$



Analysis of asymptotic behavior

Searching for the solution **in the first approximation** in the form:

$$h_z(x) = a_z e^{-(1+j)\alpha x}, \quad \text{where } \alpha_s < \alpha < \alpha_\infty,$$

where $h_z(x)$ satisfies the equation **in average**:

$$\begin{aligned} \frac{d^2 h_z}{dx^2} &= j\omega\sigma\mu_0\mu_r(h_z)h_z \implies \\ &\implies \int_0^\infty \left| \frac{d^2 h_z}{dx^2} \right| dx = \int_0^\infty \left| j\omega\sigma\mu_0\mu_r(h_z)h_z \right| dx. \end{aligned}$$

$$\begin{aligned} \alpha^2 &= \frac{\omega\sigma\mu_0}{2} \frac{\int_0^\infty \mu_r(|a_z|e^{-\alpha x})e^{-\alpha x} dx}{\int_0^\infty e^{-\alpha x} dx} \\ &= 2\alpha_0^2 \frac{\sqrt{A} \sinh^{-1}(\sqrt{A}) + 1 - \sqrt{1+A}}{A} + \alpha_1^2, \end{aligned}$$

where

$$A = 4|a_z|^2 \left(1 - (|a_x|/\gamma_1\gamma_2)^2 \right).$$



Asymptotic solution

$$\frac{d^2 h_z}{dx^2} - 2j\alpha^2 h_z = j(\omega\sigma\mu_0\mu_r(h_z) - 2\alpha^2) h_z,$$

where, according to the analyzed asymptotic behavior,

$$h_z(x) = h_{Iz} \exp(-(1+j)\alpha x + \psi(x) + o(\psi)),$$
$$\psi(0) = 0, \quad \text{and} \quad \lim_{x \rightarrow \infty} |\psi(x)| < \infty.$$

$$\psi'' - 2(1+j)\alpha\psi' = 2j \left(\alpha_0^2 \frac{2}{\sqrt{1+Ae^{-2\alpha x}} + 1} + \alpha_1^2 - \alpha^2 \right).$$

Solution for $\psi(x)$:

$$\psi(x) = (1+j) \frac{(\alpha^2 - \alpha_\infty^2)x}{2\alpha} - \frac{\alpha_0^2}{\alpha^2} \frac{2+j}{20z} \left\{ 8 - 4j + 5z - (10 - 2j)\sqrt{1+z} \right.$$
$$\left. - (6 + 2j)z \ln \frac{1 + \sqrt{1+z}}{2} + 2(1+j)F\left(j, \frac{1}{2}; 1+j; -z\right) \right\} \Bigg|_{z=Ae^{-2\alpha x}}^{z=A},$$



Hypergeometric function

$$\begin{aligned} F(a, b; c; z) &= 1 + \sum_{m=1}^{\infty} \left(\prod_{n=0}^{m-1} \frac{(a+n)(b+n)}{(c+n)} \right) \frac{z^m}{m!} \\ &= 1 + \frac{ab}{c} \frac{z}{1!} + \frac{a(a+1)b(b+1)}{c(c+1)} \frac{z^2}{2!} + \dots \end{aligned}$$

Some particular cases:

$$e^z = \lim_{k \rightarrow \infty} F\left(1, k; 1; \frac{z}{k}\right),$$

$$\cos(z) = \lim_{a, b \rightarrow \infty} F\left(a, b; \frac{1}{2}; -\frac{z^2}{4ab}\right),$$

$$\ln(1+z) = z F(1, 1; 2; -z)$$

$$F\left(j, \frac{1}{2}; 1+j; -z\right) = 1 + \sum_{n=1}^{\infty} \frac{(-1)^n (2n-1)!}{2^{2n-1} n! (n-1)!} \frac{jz^n}{n+j}.$$



Magnetic field penetration into magnetic slab. $\theta = 0^\circ$

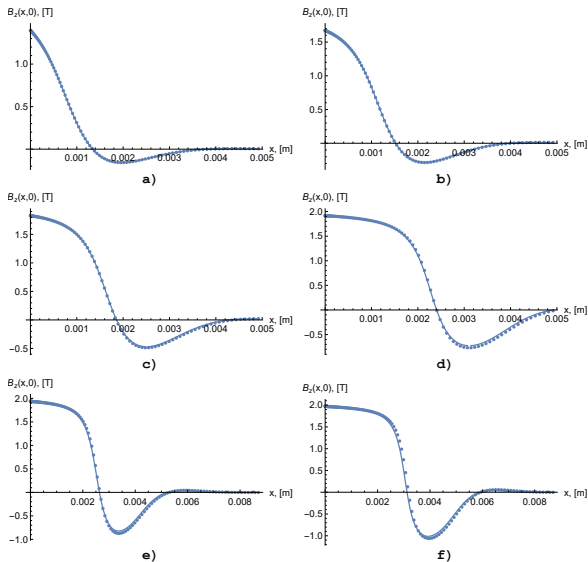


Figure 26: a) $|\mathbf{H}_I| = 1000$ A/m, b) $|\mathbf{H}_I| = 2000$ A/m, c) $|\mathbf{H}_I| = 4000$ A/m, d) $|\mathbf{H}_I| = 8000$ A/m, e) $|\mathbf{H}_I| = 10000$ A/m, f) $|\mathbf{H}_I| = 15000$ A/m



Magnetic field penetration into magnetic slab. $\theta = 45^\circ$

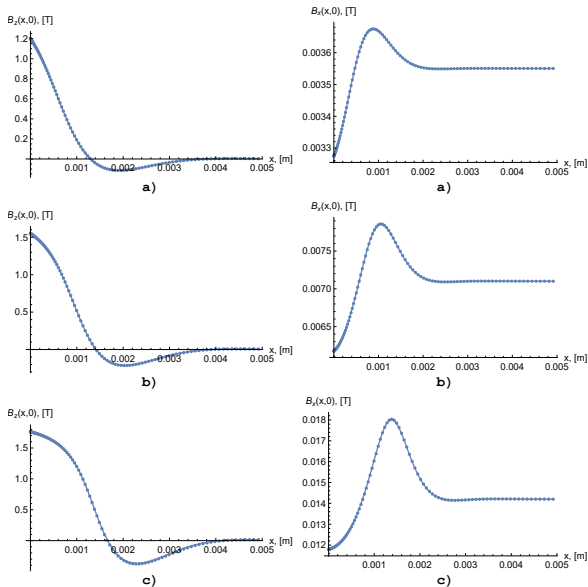


Figure 27: a) $|\mathbf{H}_I| = 1000$ A/m, b) $|\mathbf{H}_I| = 2000$ A/m, c) $|\mathbf{H}_I| = 4000$ A/m



Magnetic field penetration into magnetic slab. $\theta = 45^\circ$

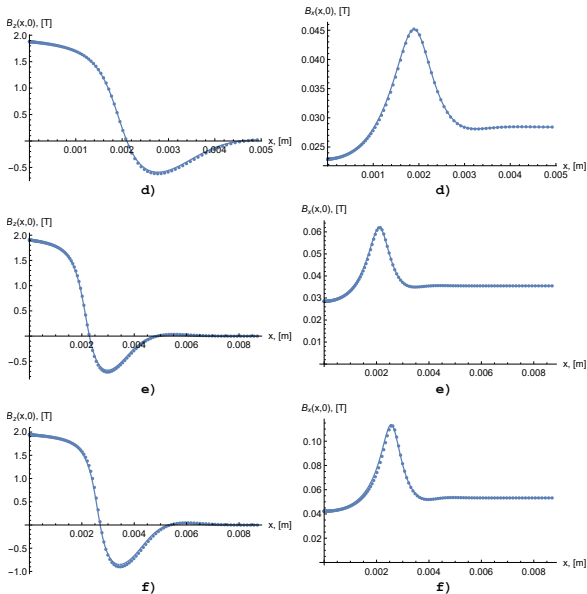


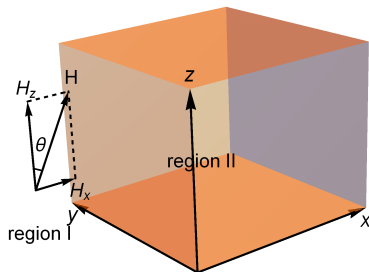
Figure 28: d) $|\mathbf{H}_I| = 8000$ A/m, e) $|\mathbf{H}_I| = 10000$ A/m, f) $|\mathbf{H}_I| = 15000$ A/m



Surface impedance

Total magnetic flux per meter below the slab surface in the tangential direction:

$$\Phi = \int_0^{\infty} B_z(x) dx = \mu_0 \int_0^{\infty} \mu_r(|\mathbf{H}(x)|) H_z(x) dx.$$



Electromotive force in the tangential direction:

$$\mathcal{E} = j\omega\Phi.$$

Current density in the tangential direction:

$$J_y(x) = -\frac{\partial H_z(x)}{\partial x}.$$

Total surface current per meter:

$$I = \int_0^{\infty} J_y(x) dx = H_{Iz}.$$



Surface impedance

Surface impedance:

$$Z_s = \frac{\mathcal{E}}{I} = \frac{j\omega\mu_0}{H_{I_z}} \int_0^\infty \mu_r(|\mathbf{H}(x)|) H_z(x) dx.$$

$$Z_s = \frac{1}{2\alpha\sigma} \left\{ (1+j)(\alpha^2 + \alpha_1^2) - \frac{4\alpha_0^2}{5A} \left(5 - 2(2+j)\sqrt{1+A} - (1-2j)F\left(j, \frac{1}{2}; 1+j; -A\right) \right) \right\}.$$



For Further Reading I



S. Maximov, J. C. Olivares-Galvan, S. Magdaleno-Adame, R. Escarela-Perez, E. Campero-Littlewood.

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For Further Reading II



R. Escarela-Perez, S. Maximov, J. C. Olivares-Galvan,
E. Melgoza, M. A. Arjona.

Effective Nonlinear Surface Impedance of Conductive Magnetic
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